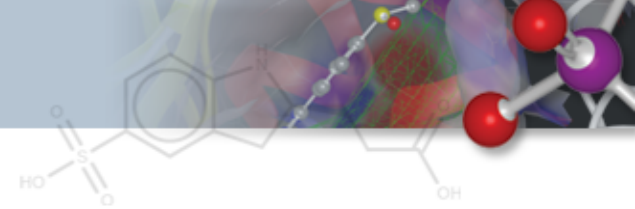


FastROCS

An OpenCL Deployment Story

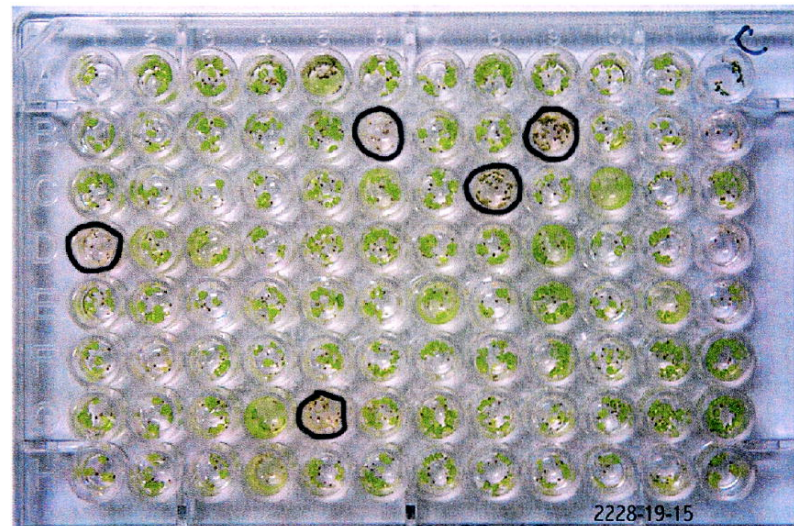
Brian Cole
Lead Technology Strategist &
Toolkit Project Manager



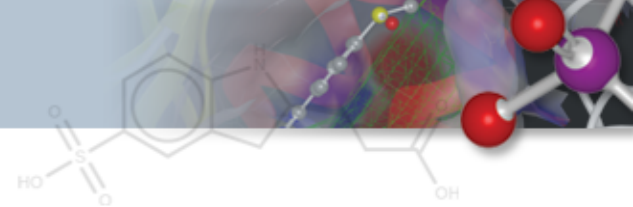
(Virtual) Screening

- Searching for the next miracle drug

- $\sim 10^{10}$ compounds
 - 1 well = \$1

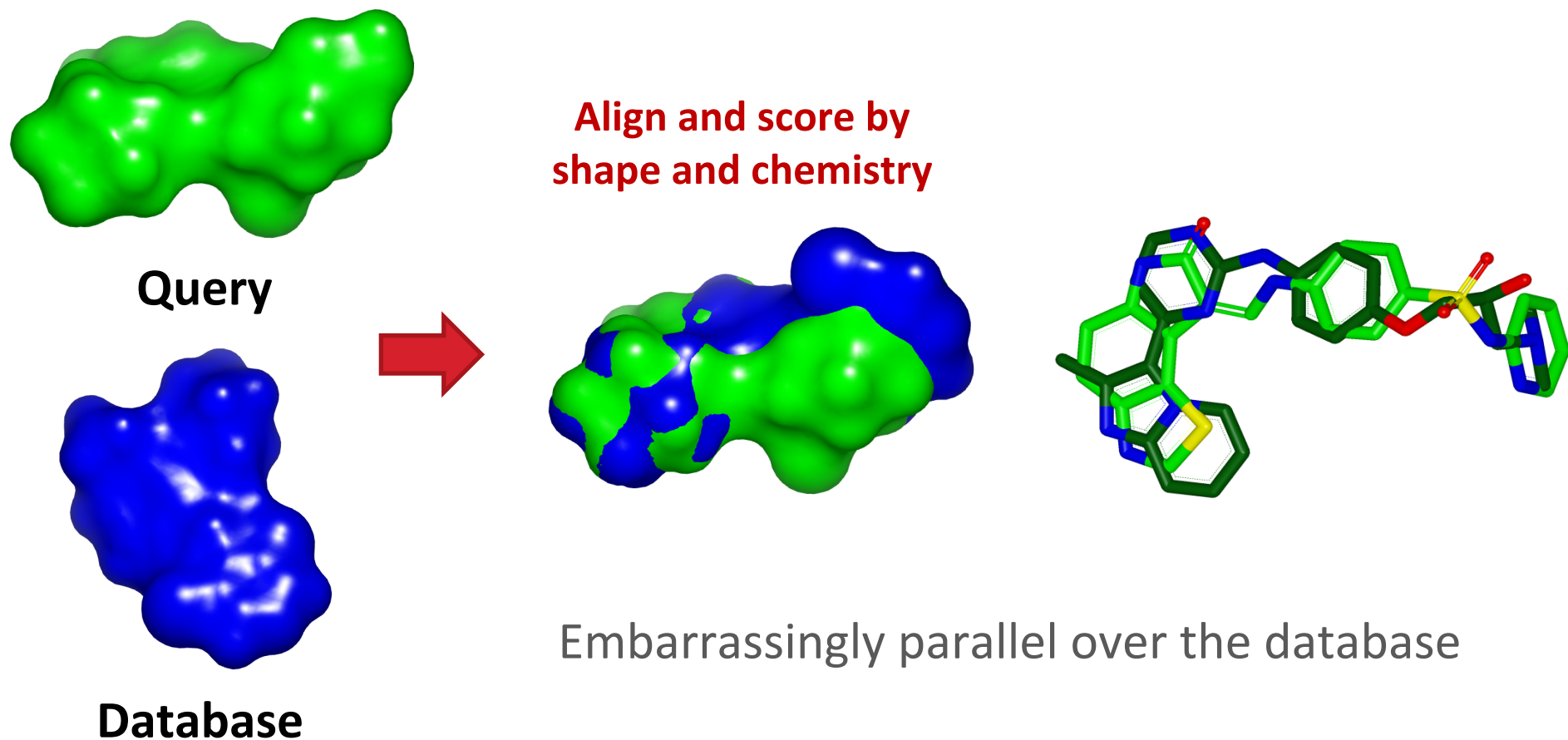


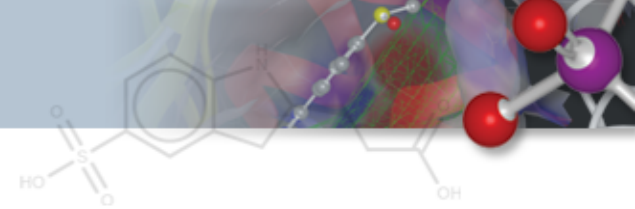
- “Drug-like” chemical space
 - $\sim 10^{33}$



What is ROCS?

Rapid Overlay of Chemical Structures: High speed ligand-based database searching tool

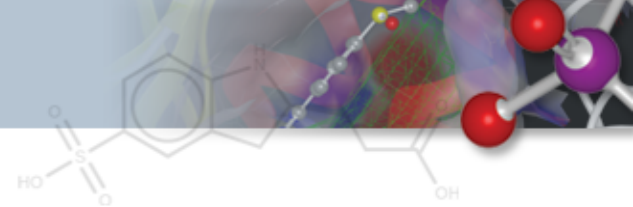




ROCS user base

- Every Pharma R&D
- Many BioTechs
- Many Universities
- National Labs and Research Centers
- Other software companies





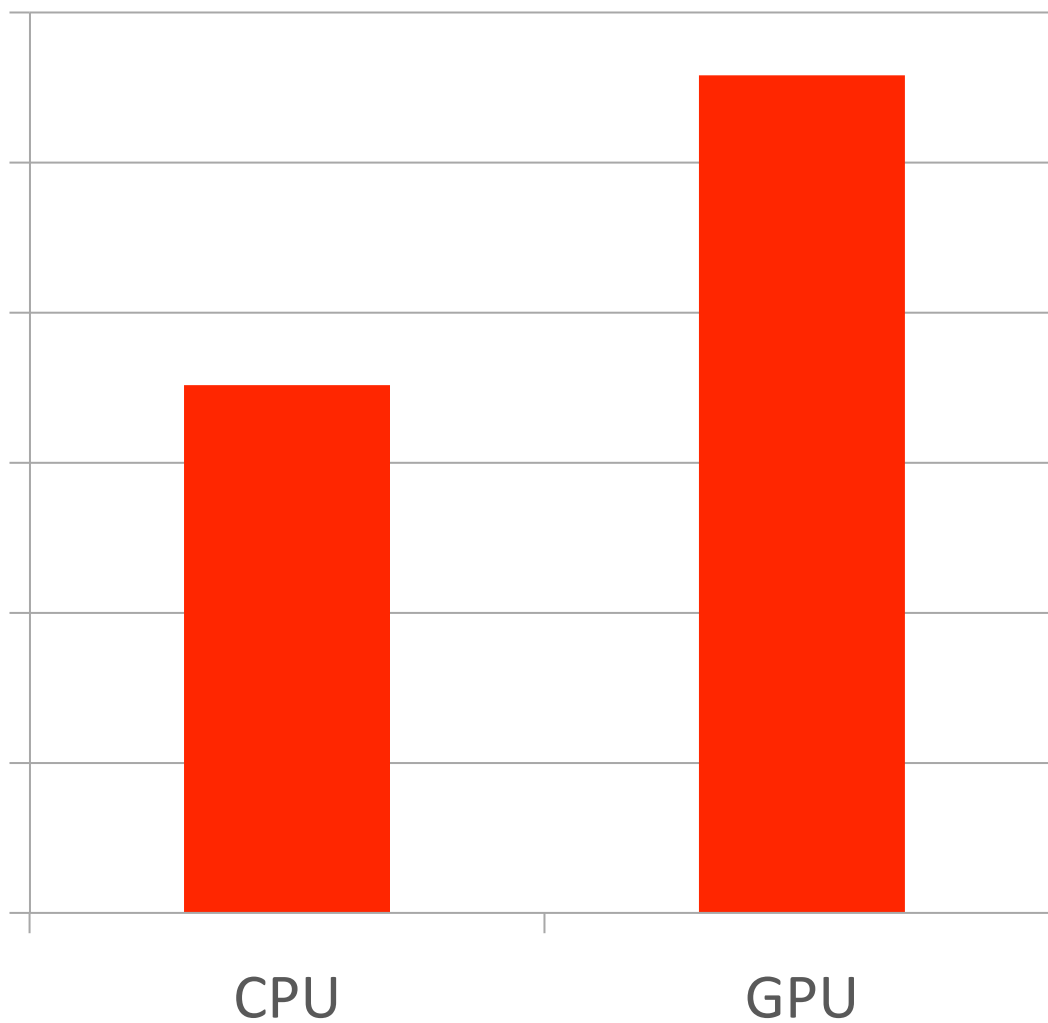
Fast ROCS

Fast Rapid Overlay of Chemical Structures

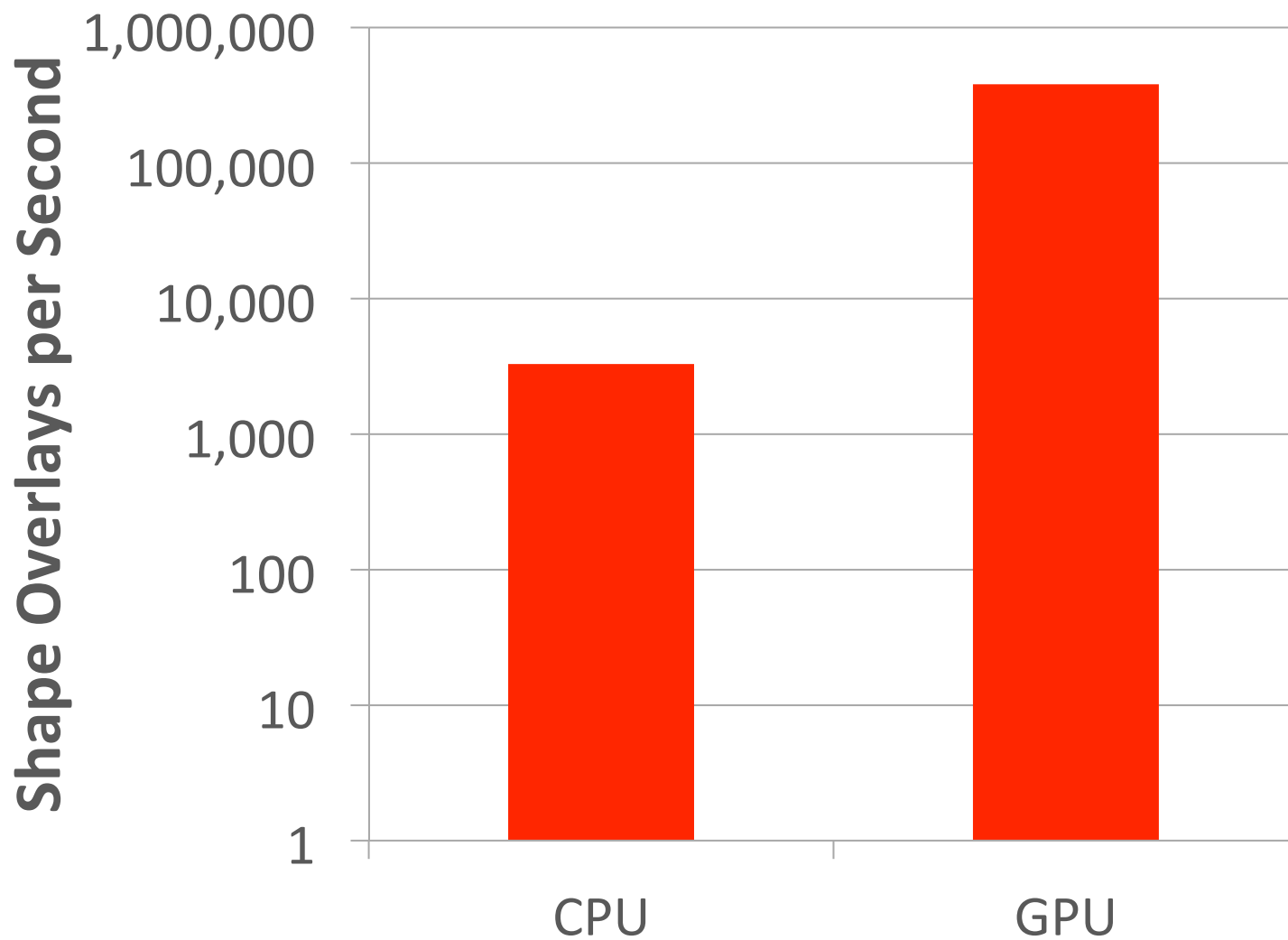
What is FastROCS?

Shape Overlays per Second

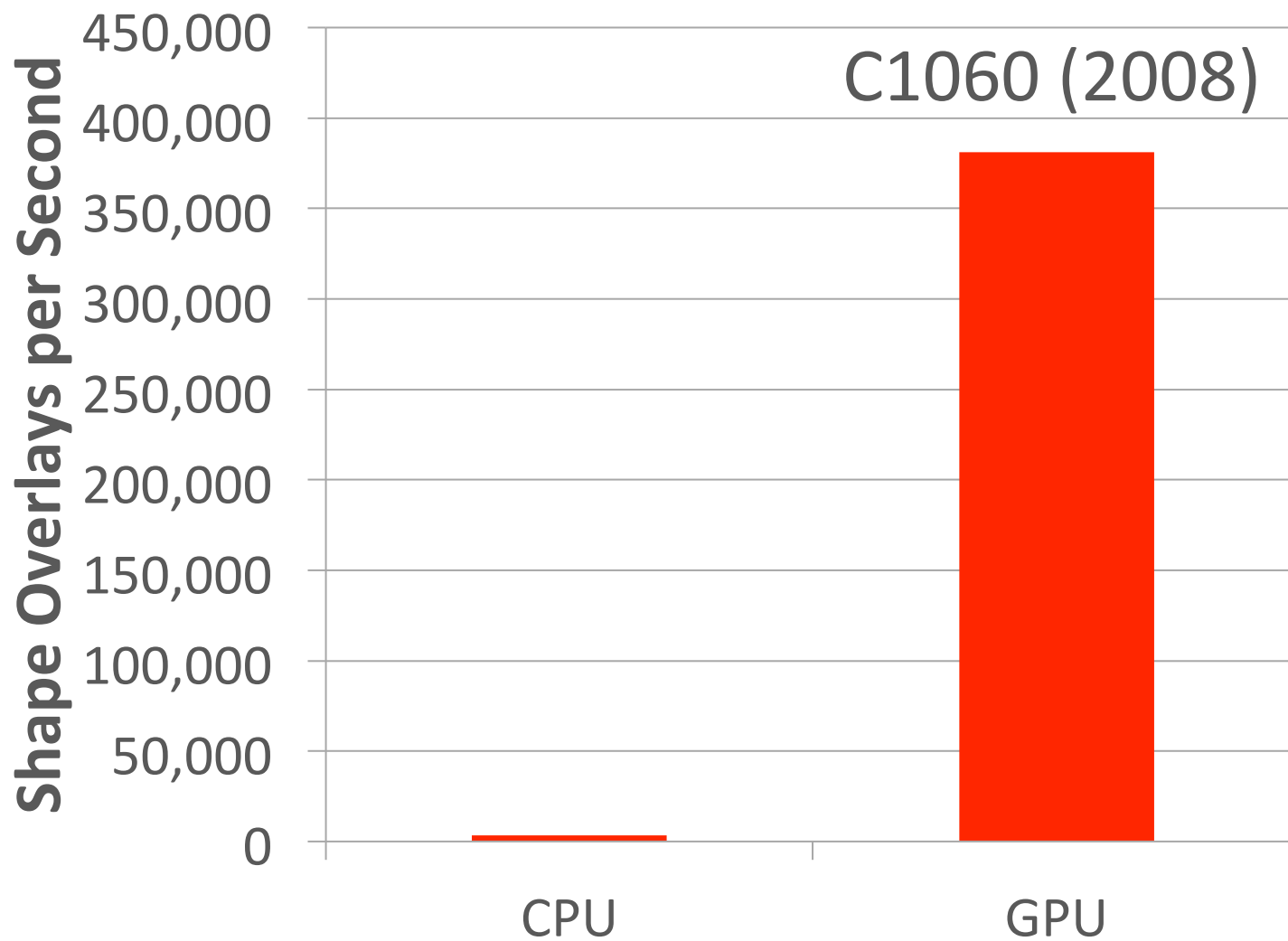
High
is
Best

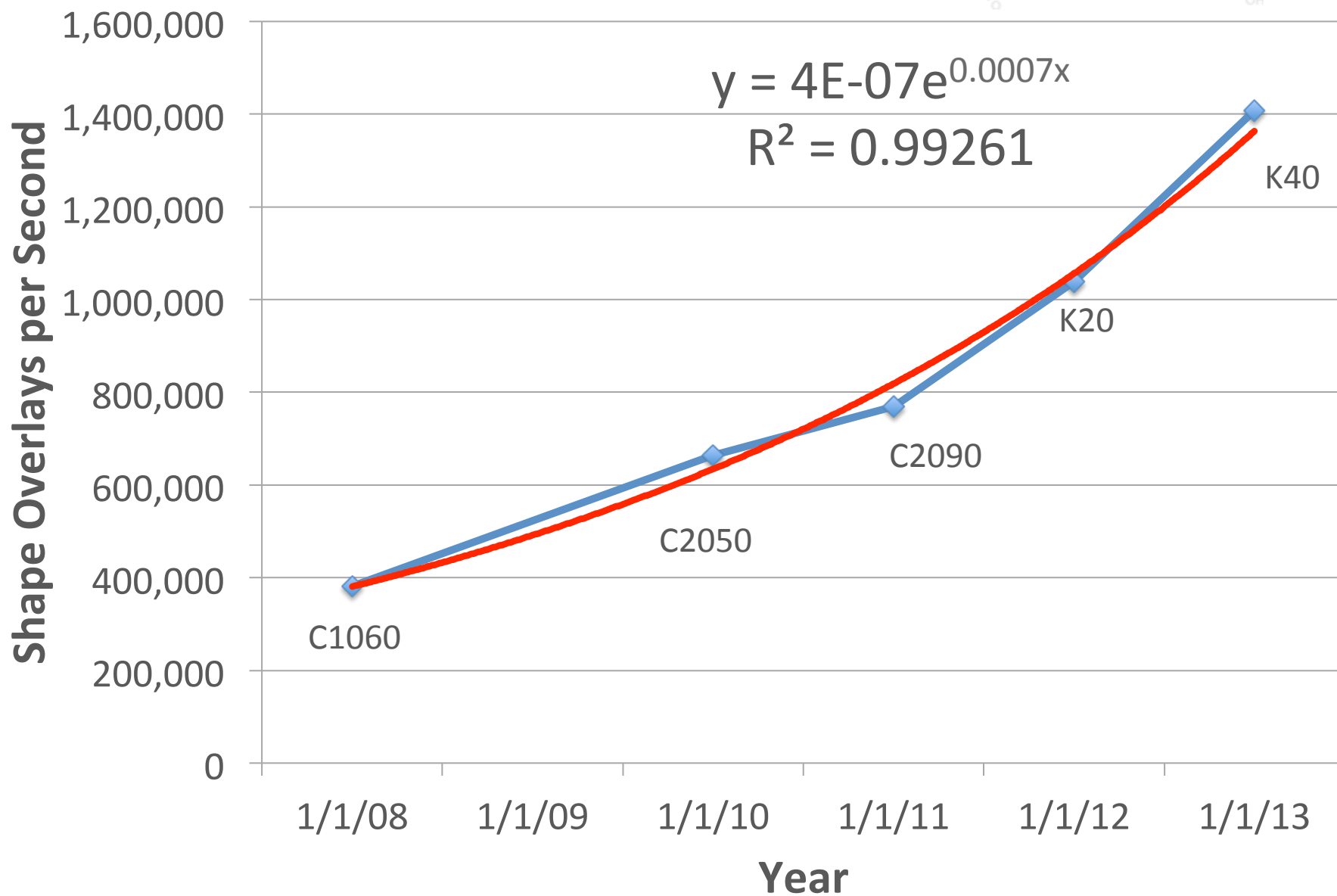
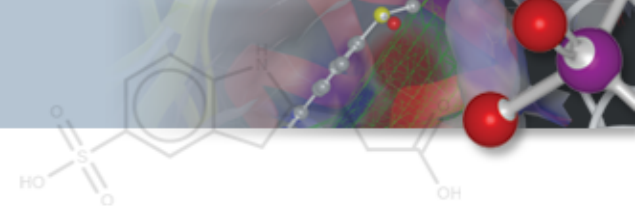


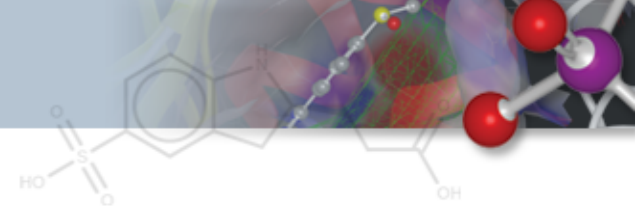
What is FastROCS?



What is FastROCS?



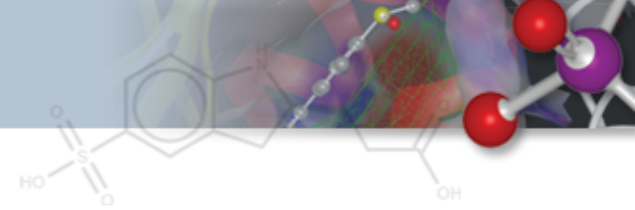




$$O(n) < O(n^2)$$

0.02	0.22	1.01	1.59	6.70	11.15	6.42	1.28	0.09	0.00
0.10	1.27	5.76	9.02	10.79	17.96	10.34	2.06	0.24	0.02
0.19	2.50	11.34	H₃N⁺	12.01	13.67	6.62	5.66	1.67	0.17
0.13	1.70	7.72	12.08	11.57	17.00	15.92	O⁻	4.02	0.41
0.03	0.40	1.81	6.43	14.94	14.13	13.23	11.31	3.34	0.34
0.00	0.05	0.97	6.52	O	15.16	12.18	3.80	3.25	0.10

Then just “clever use of game mechanics”

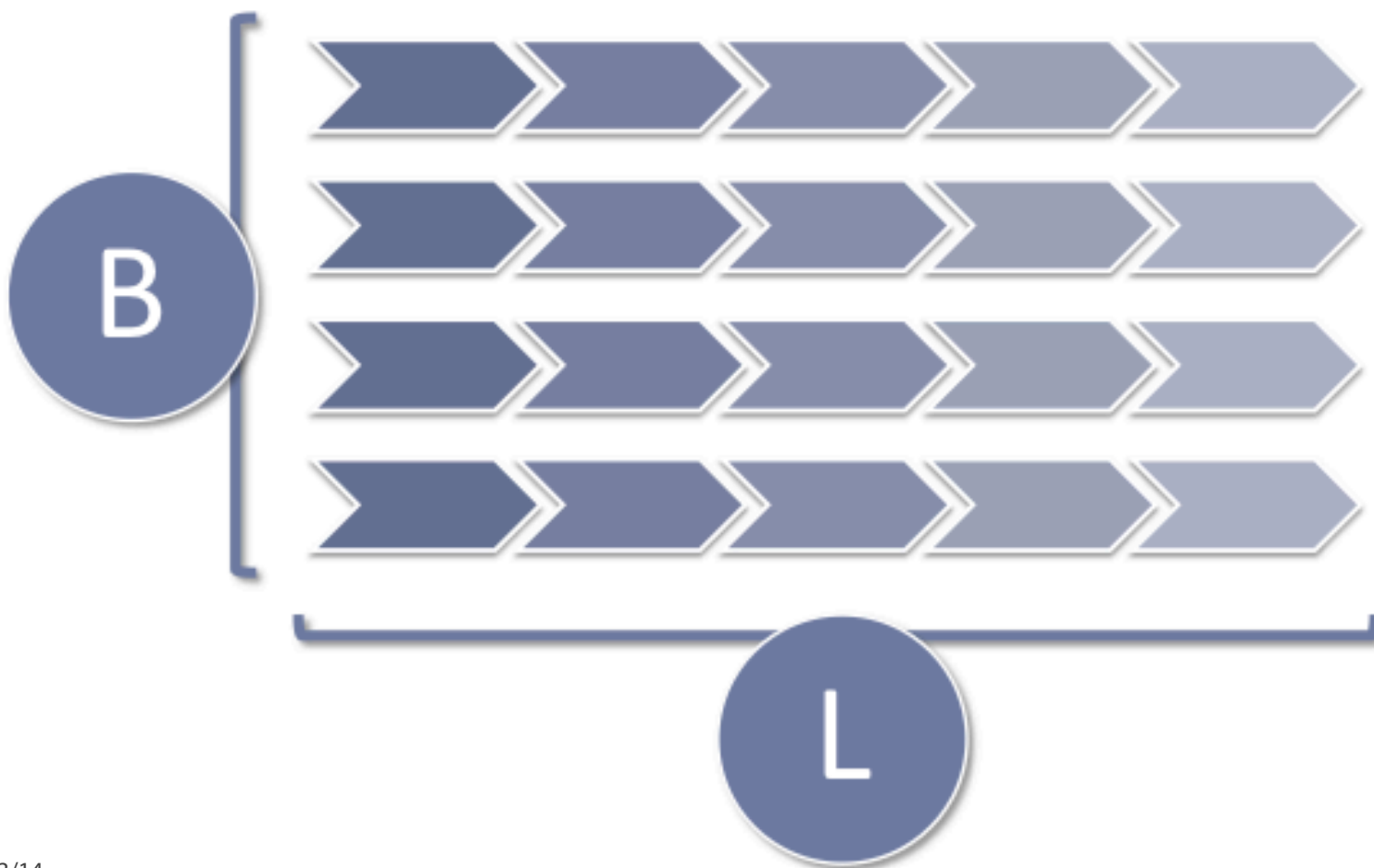


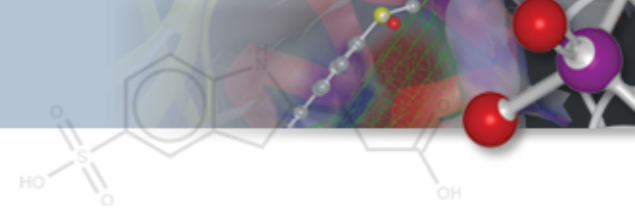
Single kernel: 679 lines of OpenCL

- A highly tuned optimizer per work item
- Working set stored in `__local` memory
 - `async_work_group_copy`
- Objective function bounded by `read_imagef`
 - `image3d_t`
 - `CL_HALF_FLOAT`
 - `sampler_t`
 - `CLK_FILTER_LINEAR`
- 64 registers per work item
 - High occupancy used to hide texture latency

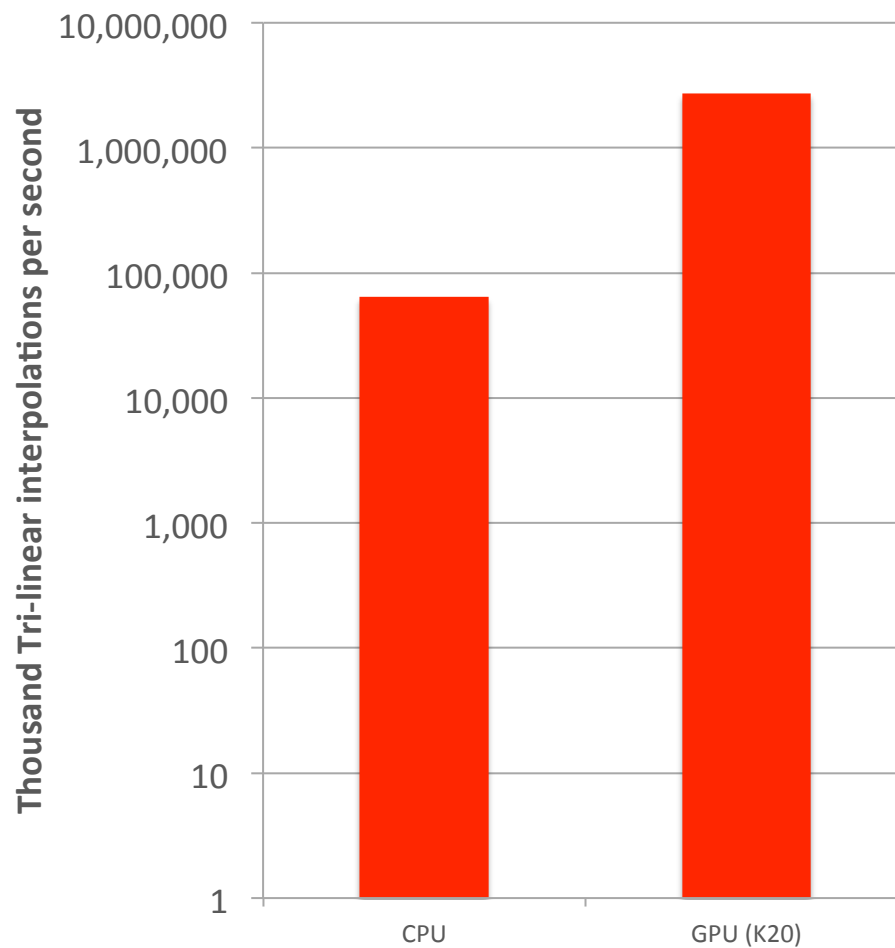
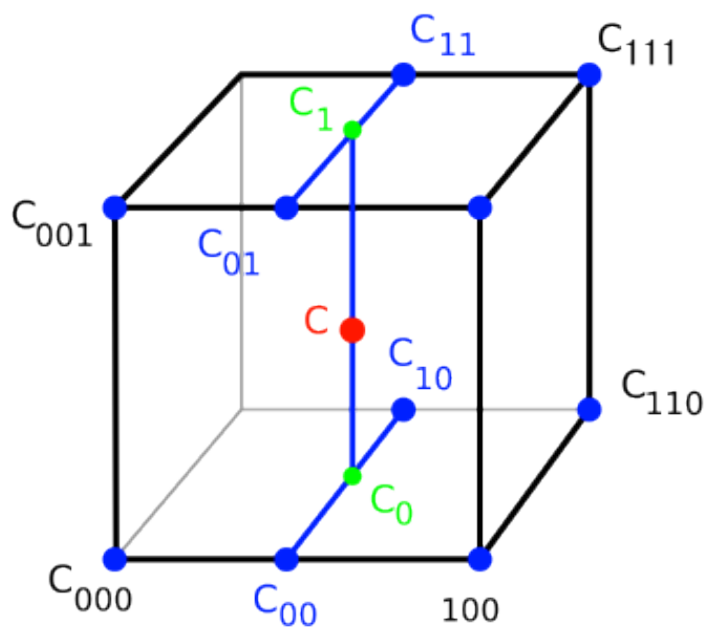
Little's Law: Embarrassingly parallel's best friend

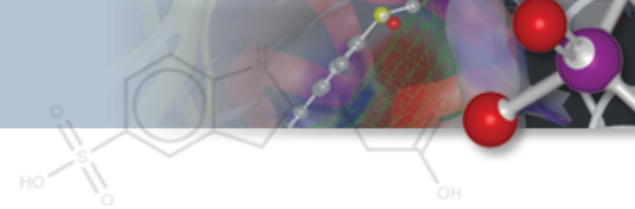
$$\text{Bandwidth} \times \text{Latency} = \text{Concurrency}$$





Tri-linear interpolation throughput



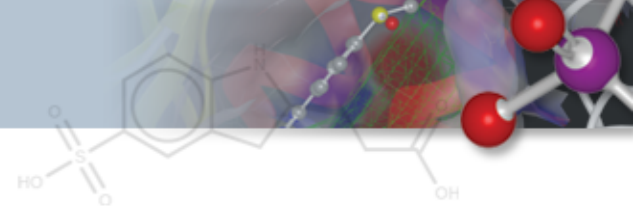


ROCS user base

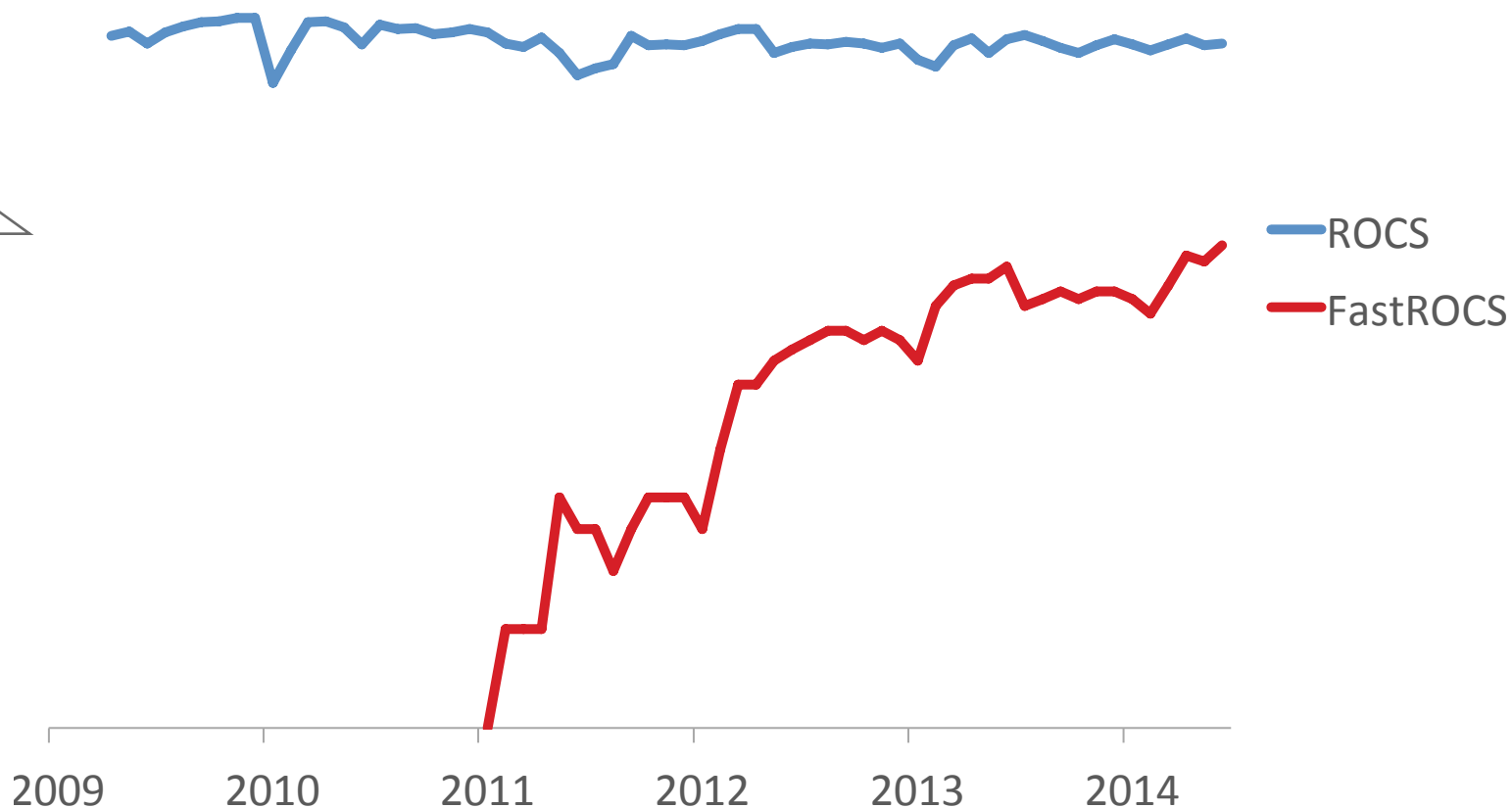
- Every Pharma R&D
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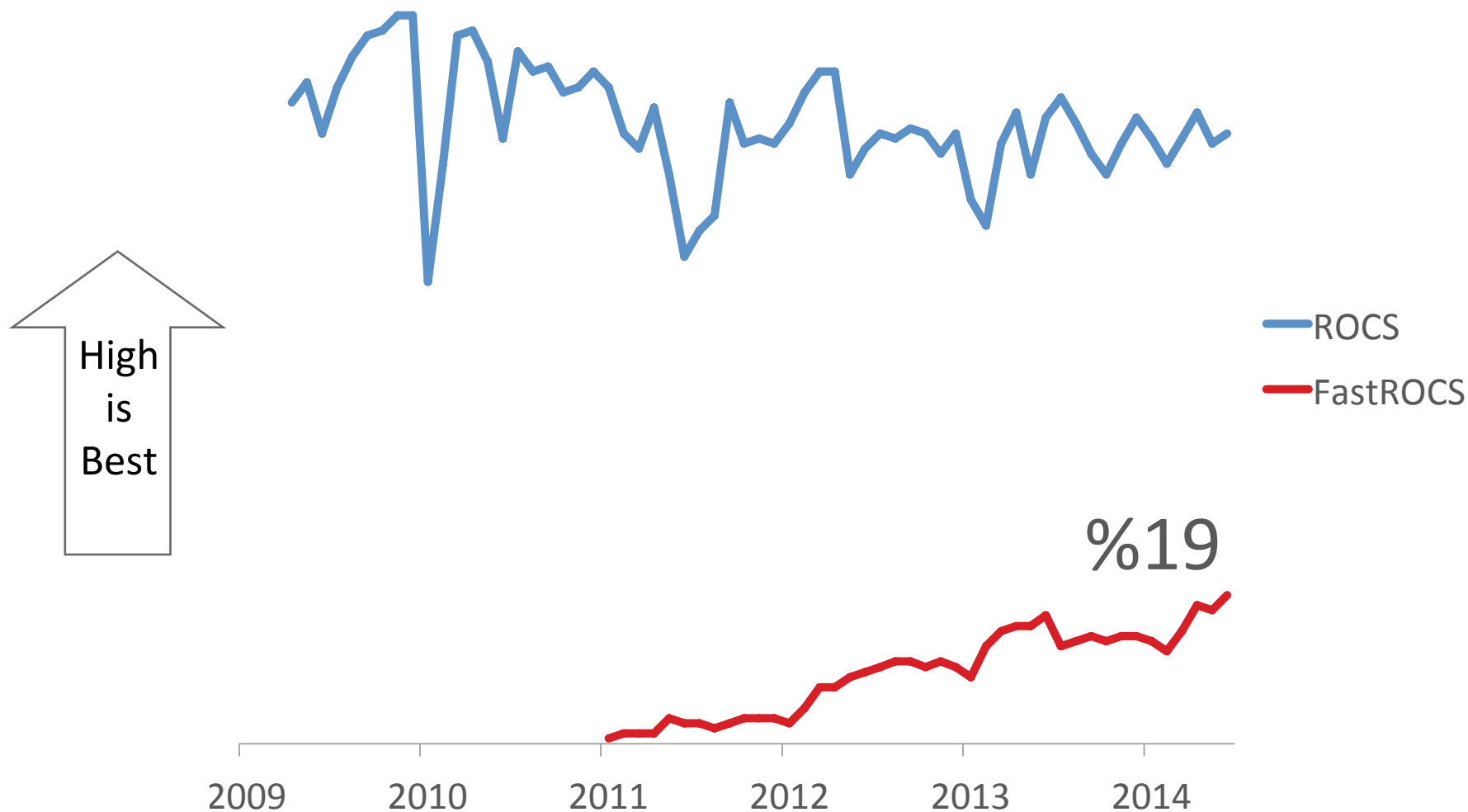
Licenses by month

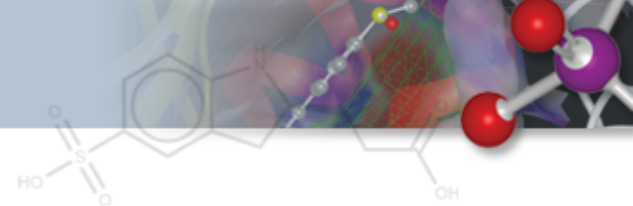


High
is
Best

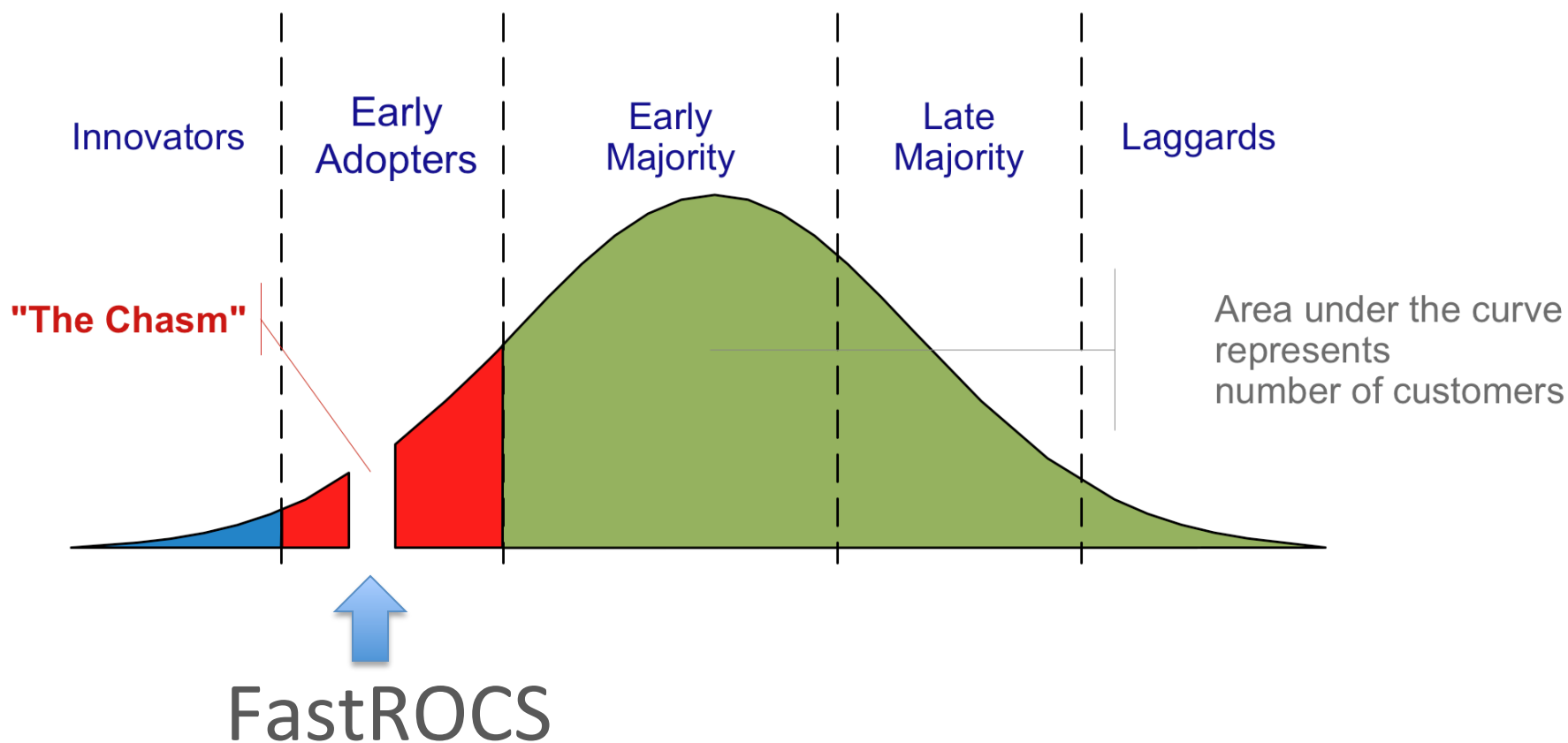


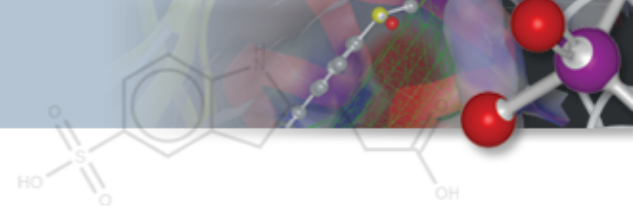
Licenses by month (linear scale)





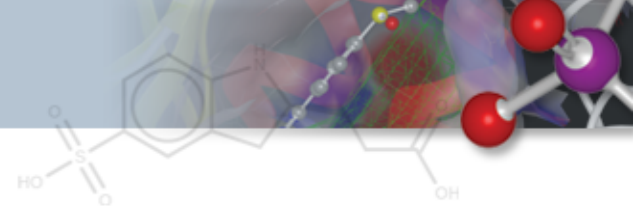
Technology Adoption Lifecycle





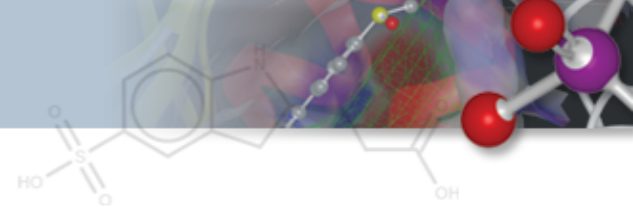
What's in the “chasm”?

- “GPUs are hard to deploy”
- “GPUs are hard to maintain”
- “The results aren't bitwise comparable”
- “There's nothing else to run on the GPU”



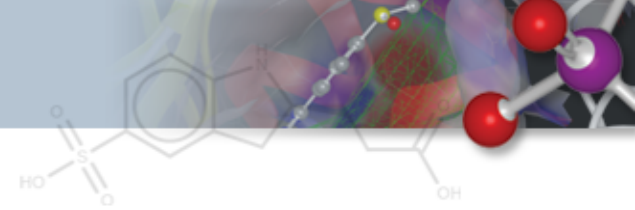
ROCS quick start guide

- `tar -xzf ROCS-3.1.1-RHEL5-x64.tar.gz`
- `openeye/bin/rocs query.sdf database.oeb.gz`



FastROCS quick start

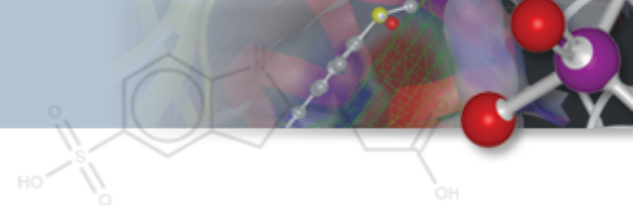
- `ctrl-alt-F1` (to switch to a non X-server terminal)
- `login as root`
- `/sbin/init 3` (to turn off the X-server)
- `./NVIDIA-Linux-x86_64-285.05.09.run`
- `reboot`
- `./cuda.sh` to give `/dev/nvidia*` correct permissions
- `tar -xzf fastrocs-1.3.1-RHEL5-x64-OpenCL-1.1-CUDA-4.1.tar.gz`
- `openeye/bin/ShapeDatabaseServer.py database.oeb.gz`
- `openeye/bin/ShapeDatabaseClient.py localhost:8080 query.sdf out.sdf`



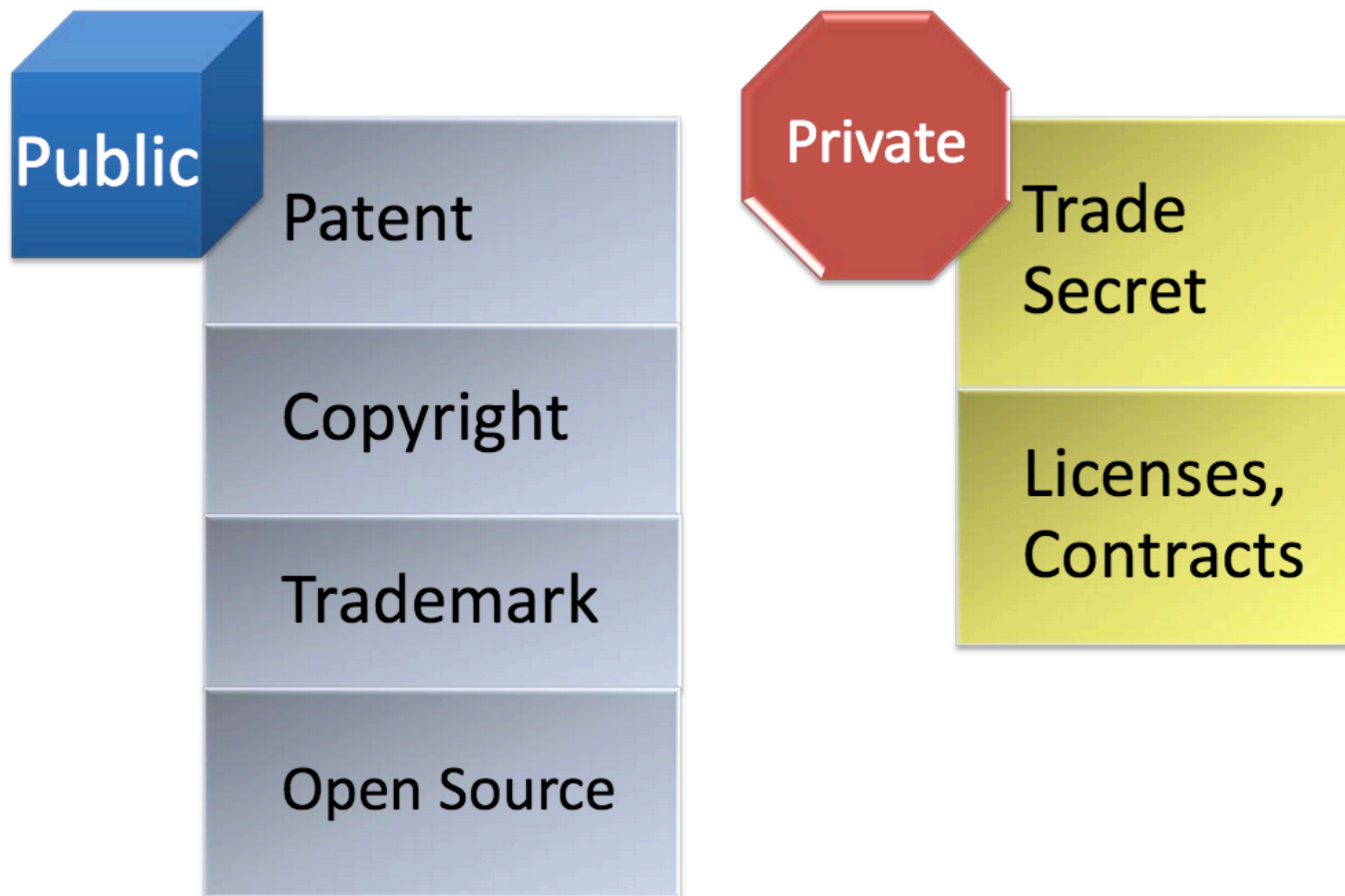
This is even worse!

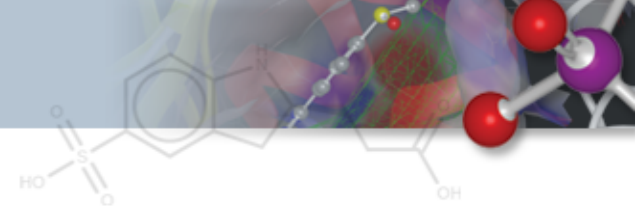
fastrocs-1.3.1-RHEL5-x64-OpenCL-1.1-CUDA-4.1.tar.gz

NVidia OpenCL binaries are tightly
locked to a particular driver version



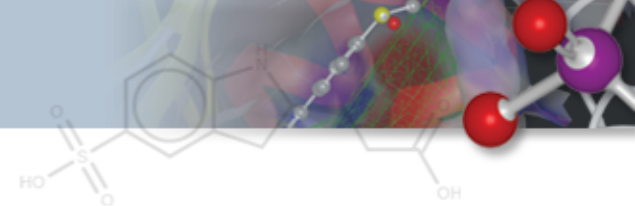
Protecting our investment





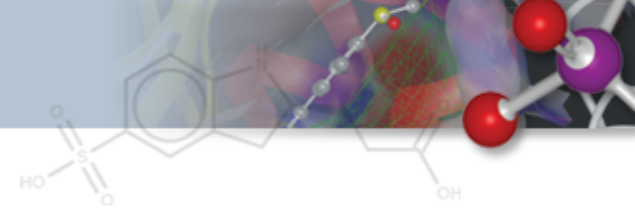
Trade secrets require due diligence

- We can't ship embedded OpenCL source code
- OpenCL SPIR is a great solution to this
 - Please support it!
- For now
 - Compile towards a specific NVidia driver
 - `clCreateProgramWithBinary`

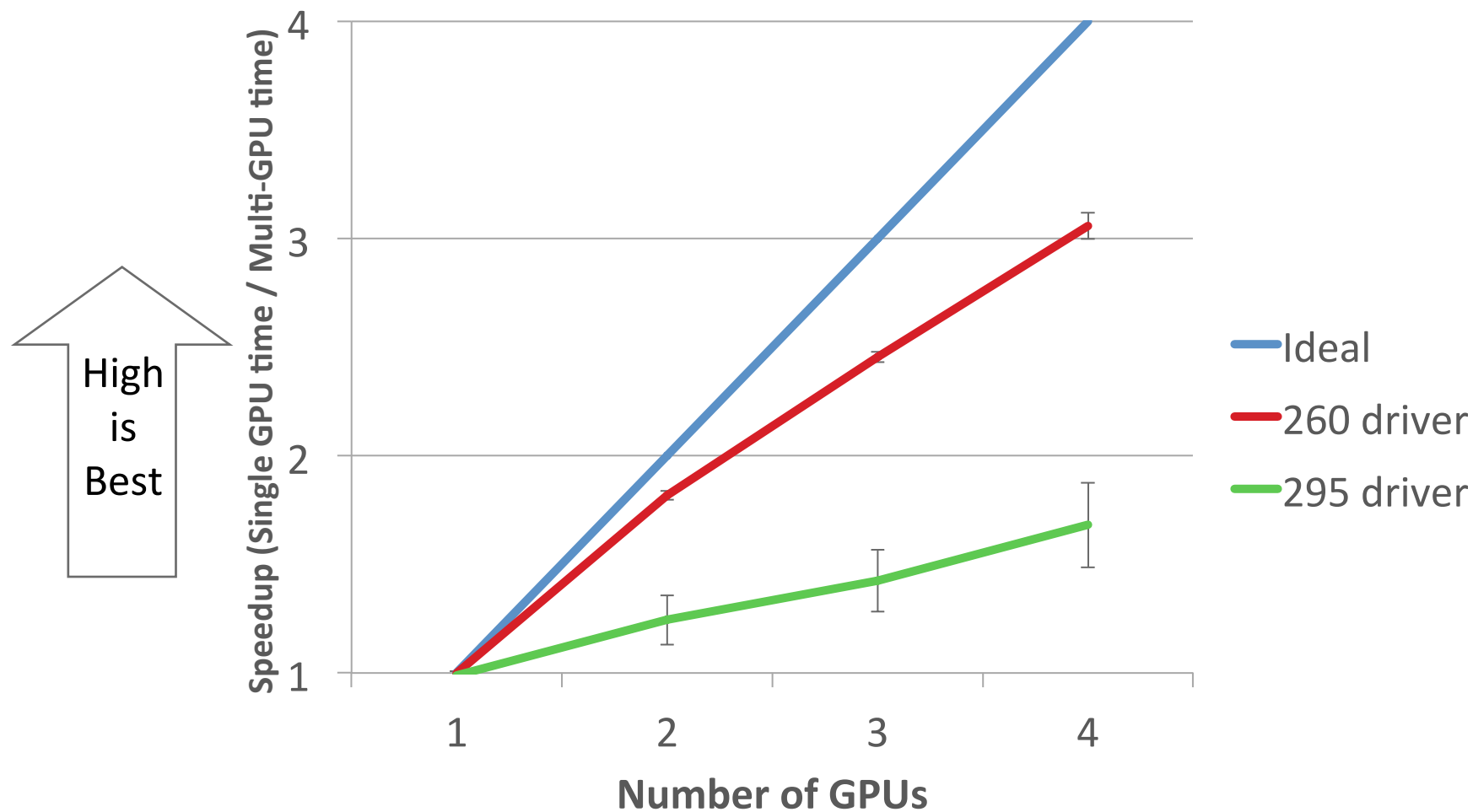


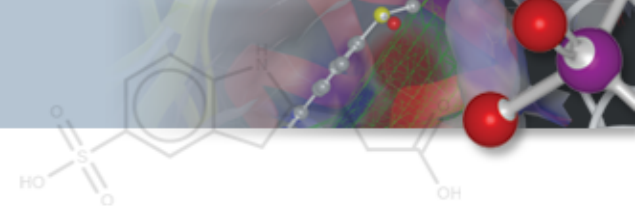
What's in the "chasm"?

- "GPUs are hard to deploy"
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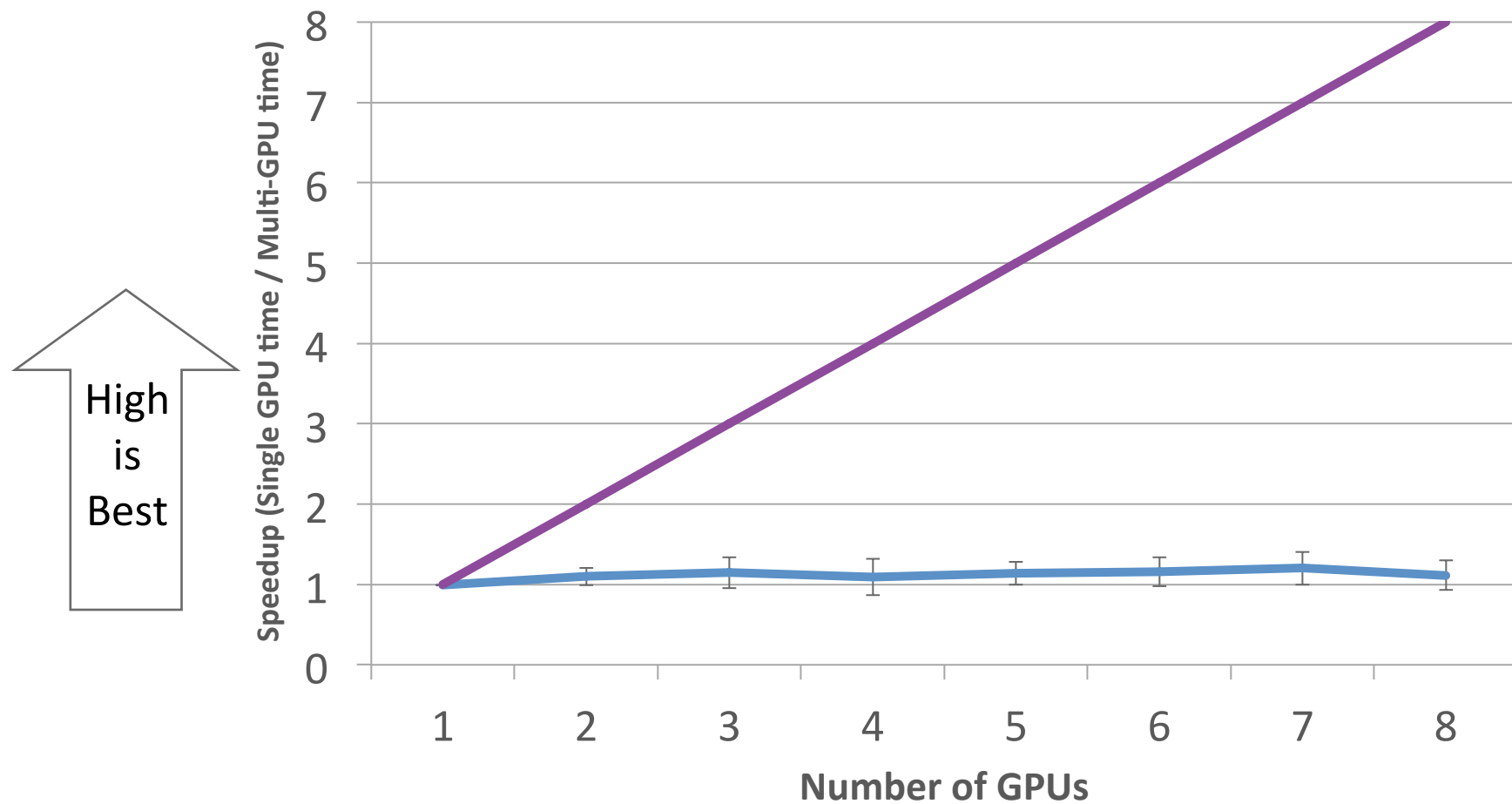


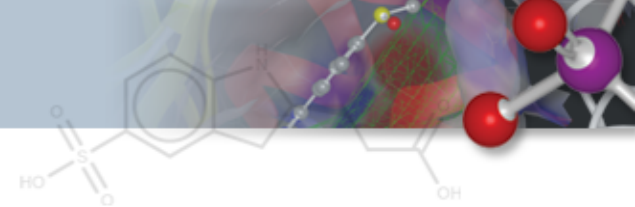
Scalability between drivers (4x C2050)





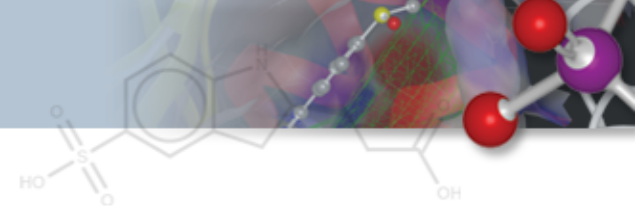
Really bad for 8x M2090





Ways to transfer to device

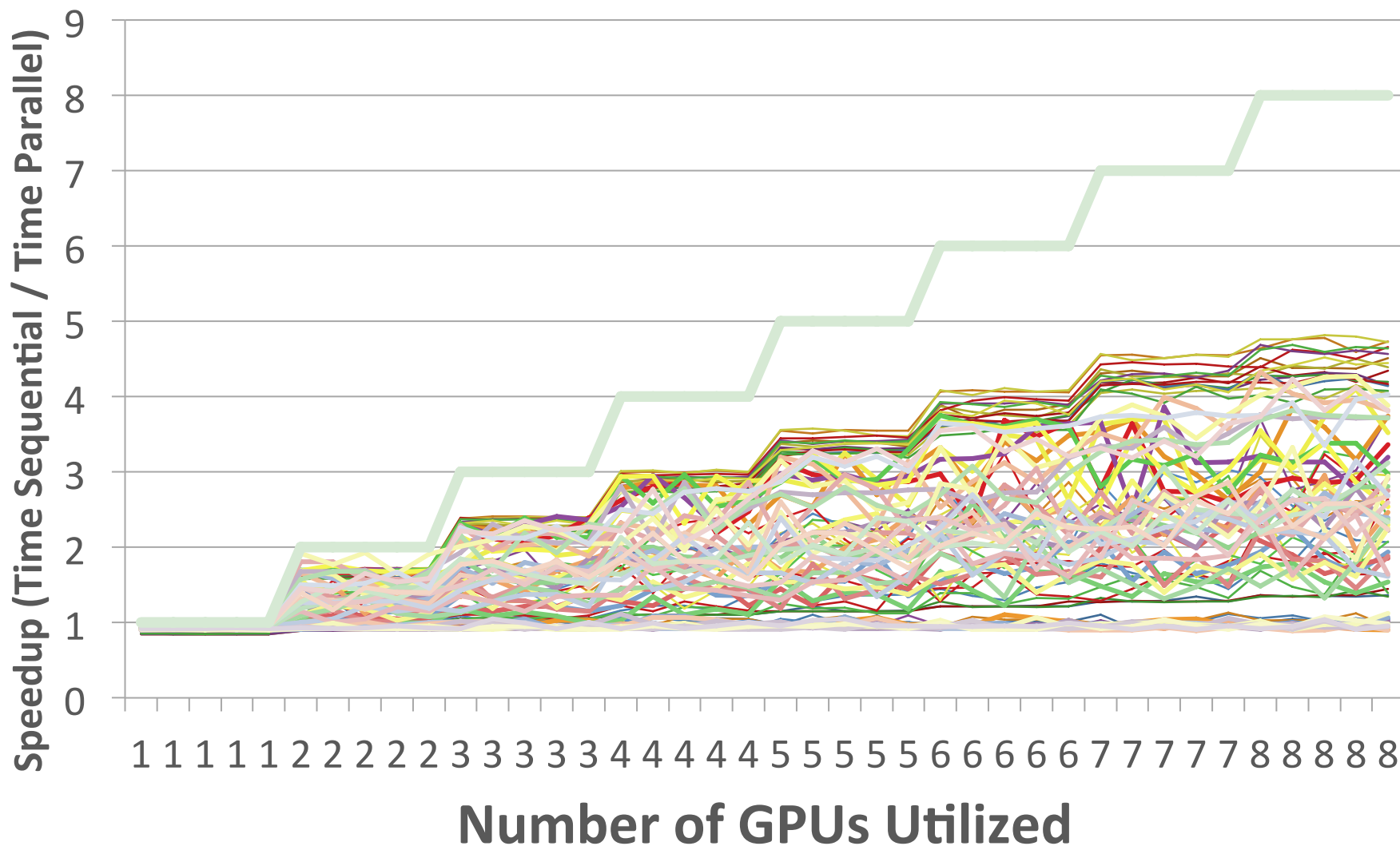
- `CL_MEM_USE_HOST_PTR`
 - `kernelBuf = clCreateBuffer(CL_MEM_USE_HOST_PTR)`
- `CL_MEM_ALLOC_HOST_PTR|CL_MEM_COPY_HOST_PTR`
 - `kernelBuf = clCreateBuffer(CL_MEM_ALLOC_HOST_PTR|CL_MEM_COPY_HOST_PTR)`
- `CL_MEM_ALLOC_HOST_PTR`
 - `kernelBuf = clCreateBuffer(CL_MEM_ALLOC_HOST_PTR)` - cacheable
 - `ptr = clEnqueueMapBuffer(kernelBuf, CL_MAP_WRITE)`
 - `memcpy(ptr, data)`
 - `clEnqueueUnmapMemObject(ptr)`
- `clEnqueueMapBuffer`
 - `kernelBuf = clCreateBuffer()` - cacheable
 - `ptr = clEnqueueMapBuffer(kernelBuf, CL_MAP_WRITE)`
 - `memcpy(ptr, data)`
 - `clEnqueueUnmapMemObject(ptr)`
- `clEnqueueWriteBuffer`
 - `kernelBuf = clCreateBuffer()` - cacheable
 - `clEnqueueWriteBuffer(kernelBuf, data)`
- `oclCopyCompute`
 - `pinnedBuf = clCreateBuffer(CL_MEM_ALLOC_HOST_PTR|CL_MEM_READ_WRITE)` – cacheable
 - `pinnedPtr = clEnqueueMapBuffer(pinnedBuf, CL_MAP_WRITE)` – cacheable
 - `memcpy(pinnedPtr, data)`
 - `kernelBuf = clCreateBuffer()` – cacheable
 - `clEnqueueWriteBuffer(kernelBuf, pinnedPtr)`

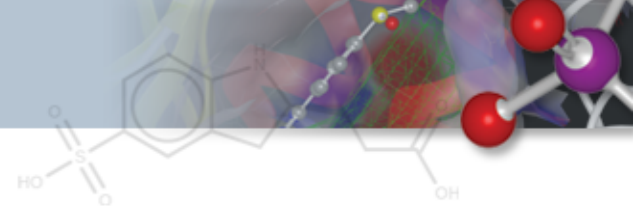


Ways to transfer from device

- `CL_MEM_ALLOC_HOST_PTR`
 - `kernelBuf = clCreateBuffer(CL_MEM_ALLOC_HOST_PTR)` - cacheable
 - `ptr = clEnqueueMapBuffer(kernelBuf, CL_MAP_WRITE)`
 - `memcpy(data, ptr)`
 - `clEnqueueUnmapMemObject(ptr)`
- `clEnqueueMapBuffer`
 - `kernelBuf = clCreateBuffer()` - cacheable
 - `ptr = clEnqueueMapBuffer(kernelBuf, CL_MAP_WRITE)`
 - `memcpy(data, ptr)`
 - `clEnqueueUnmapMemObject(ptr)`
- `clEnqueueReadBuffer`
 - `kernelBuf = clCreateBuffer()` - cacheable
 - `clEnqueueWriteBuffer(kernelBuf, data)`
- `oclCopyCompute`
 - `pinnedBuf = clCreateBuffer(CL_MEM_ALLOC_HOST_PTR|CL_MEM_READ_WRITE)` – cacheable
 - `pinnedPtr = clEnqueueMapBuffer(pinnedBuf, CL_MAP_WRITE)` – cacheable
 - `memcpy(pinnedPtr, data)`
 - `kernelBuf = clCreateBuffer()` – cacheable
 - `clEnqueueReadBuffer(kernelBuf, pinnedPtr)`

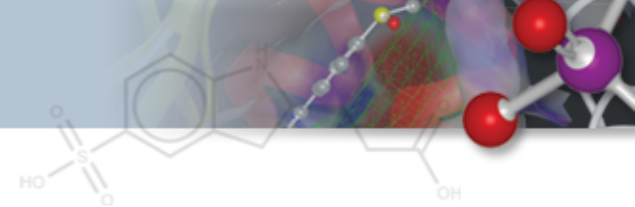
FastROCS scalability across 8x M2070





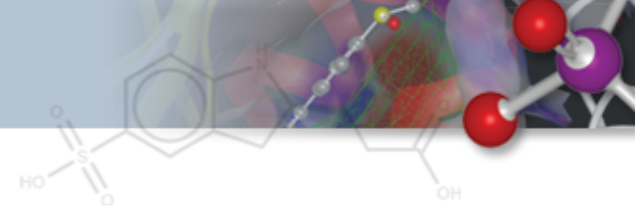
Lessons from the mess

- `clEnqueueWriteBuffer > clEnqueueMapBuffer`
- `clEnqueueMapBuffer >> clEnqueueReadBuffer`
- `CL_MEM_*` constants aren't worth the effort

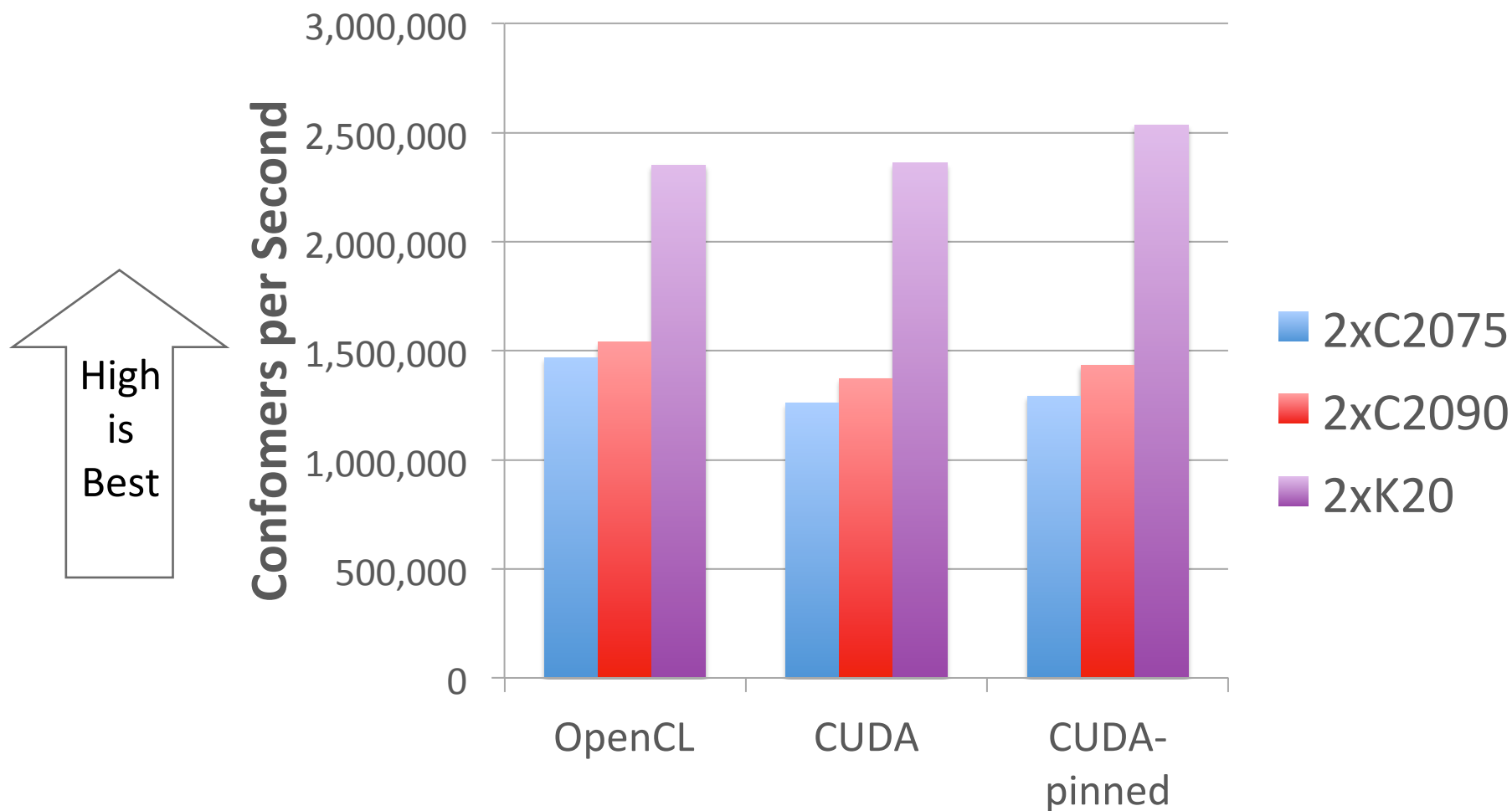


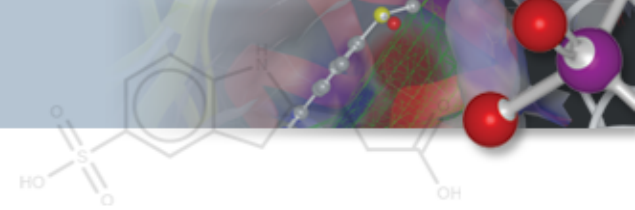
CUDA?

- Serious customers will only use NVidia cards
- Pinned memory
- Better support for binaries and compatibility
- CUDA support >> OpenCL support

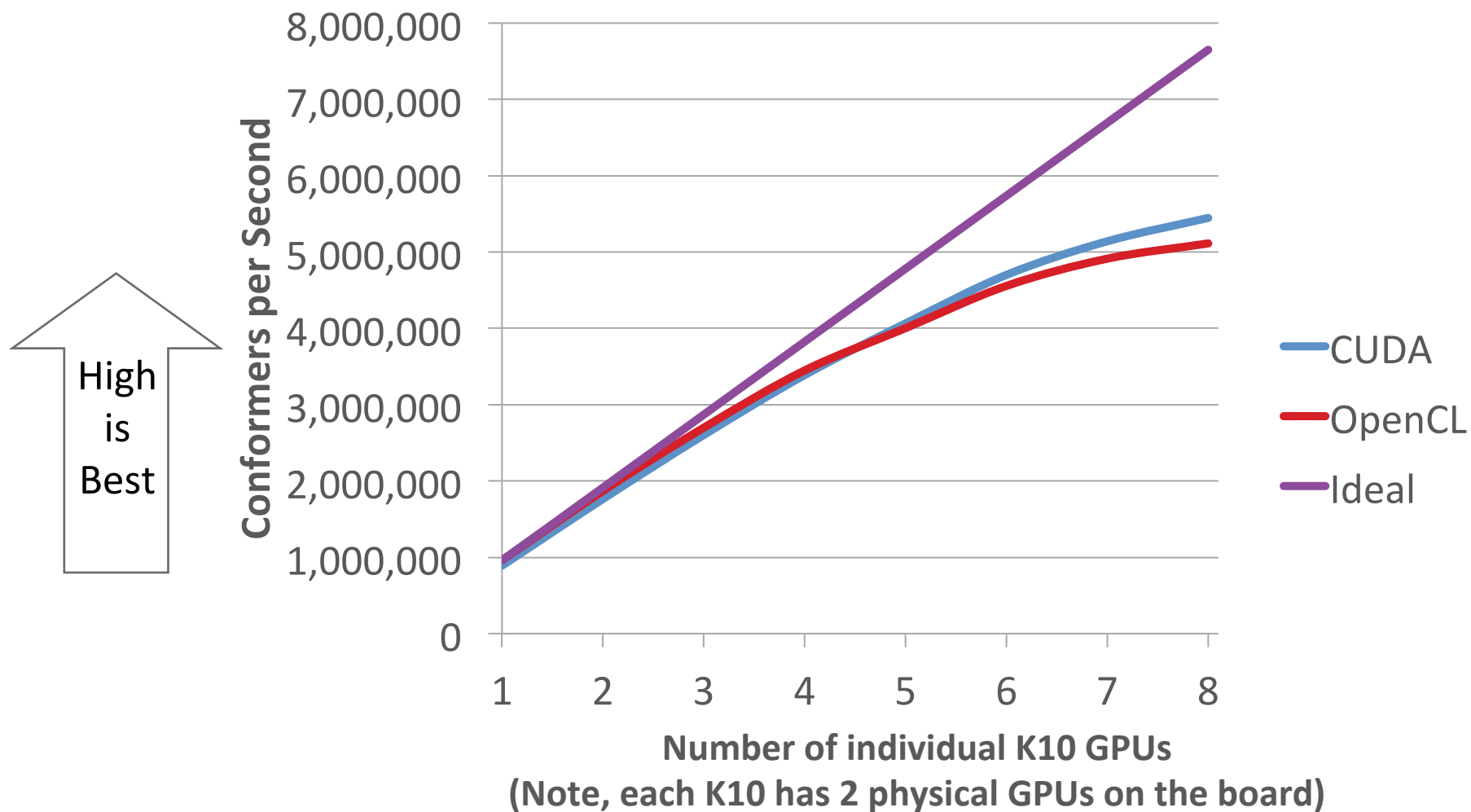


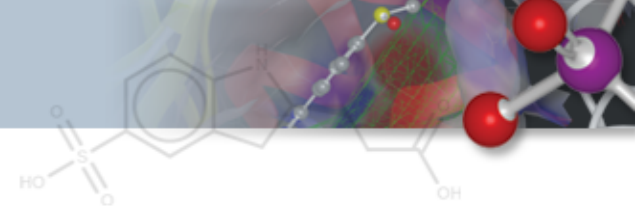
FastROCS CUDA port





CUDA Scaling?

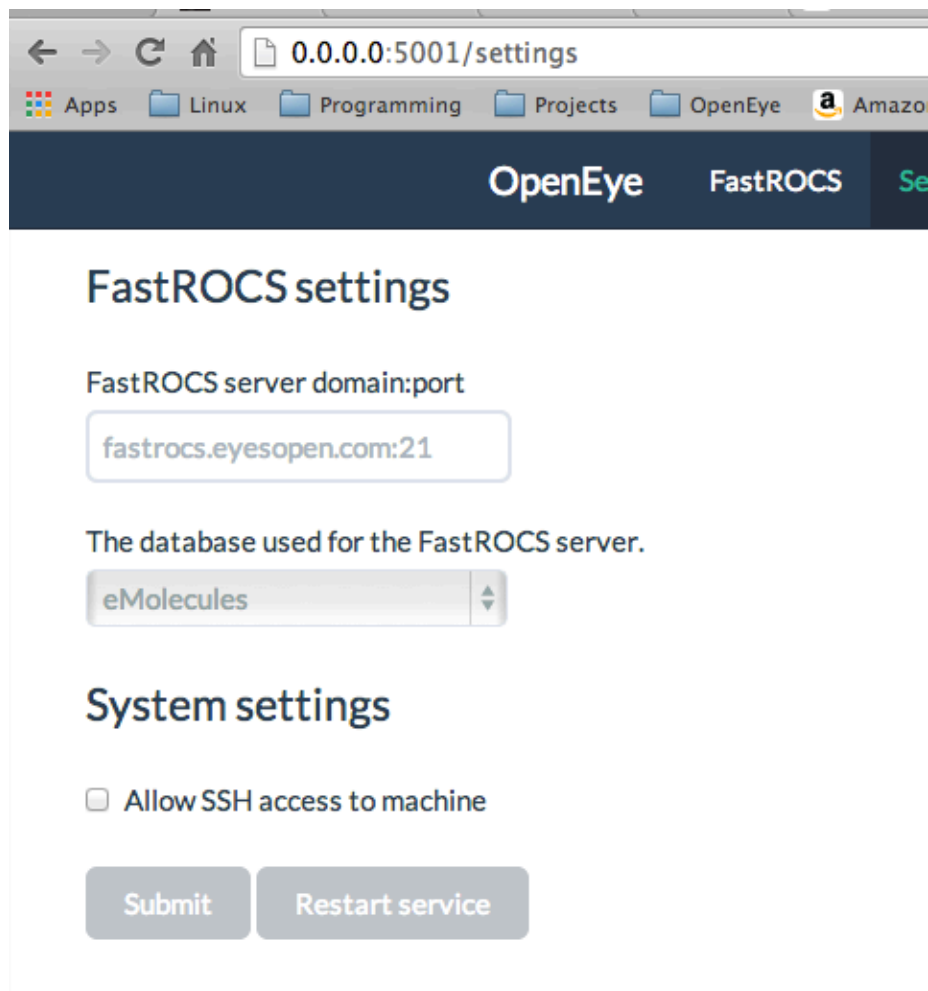




CUDA vs OpenCL: Ding Ding!

- Portability vs Innovation
- NVidia vs Intel and AMD
- Open vs Proprietary
- Customers don't care...

FastROCS Instrument

A screenshot of a web browser displaying the FastROCS settings page. The browser's address bar shows '0.0.0.0:5001/settings'. The page has a dark blue header with 'OpenEye' and 'FastROCS' logos. The main content area is titled 'FastROCS settings' and includes a form for 'FastROCS server domain:port' with the value 'fastrocs.eyesopen.com:21'. Below this is a section for 'The database used for the FastROCS server.' with a dropdown menu set to 'eMolecules'. A 'System settings' section contains a checkbox for 'Allow SSH access to machine' which is currently unchecked. At the bottom are two buttons: 'Submit' and 'Restart service'.

← → ↻ 🏠 0.0.0.0:5001/settings

Apps Linux Programming Projects OpenEye Amazon

OpenEye FastROCS

FastROCS settings

FastROCS server domain:port

fastrocs.eyesopen.com:21

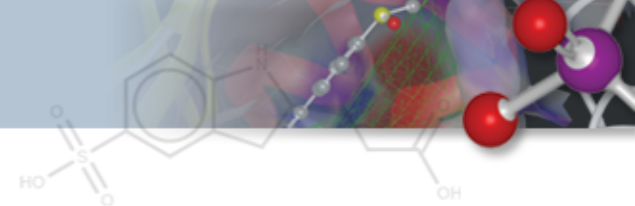
The database used for the FastROCS server.

eMolecules

System settings

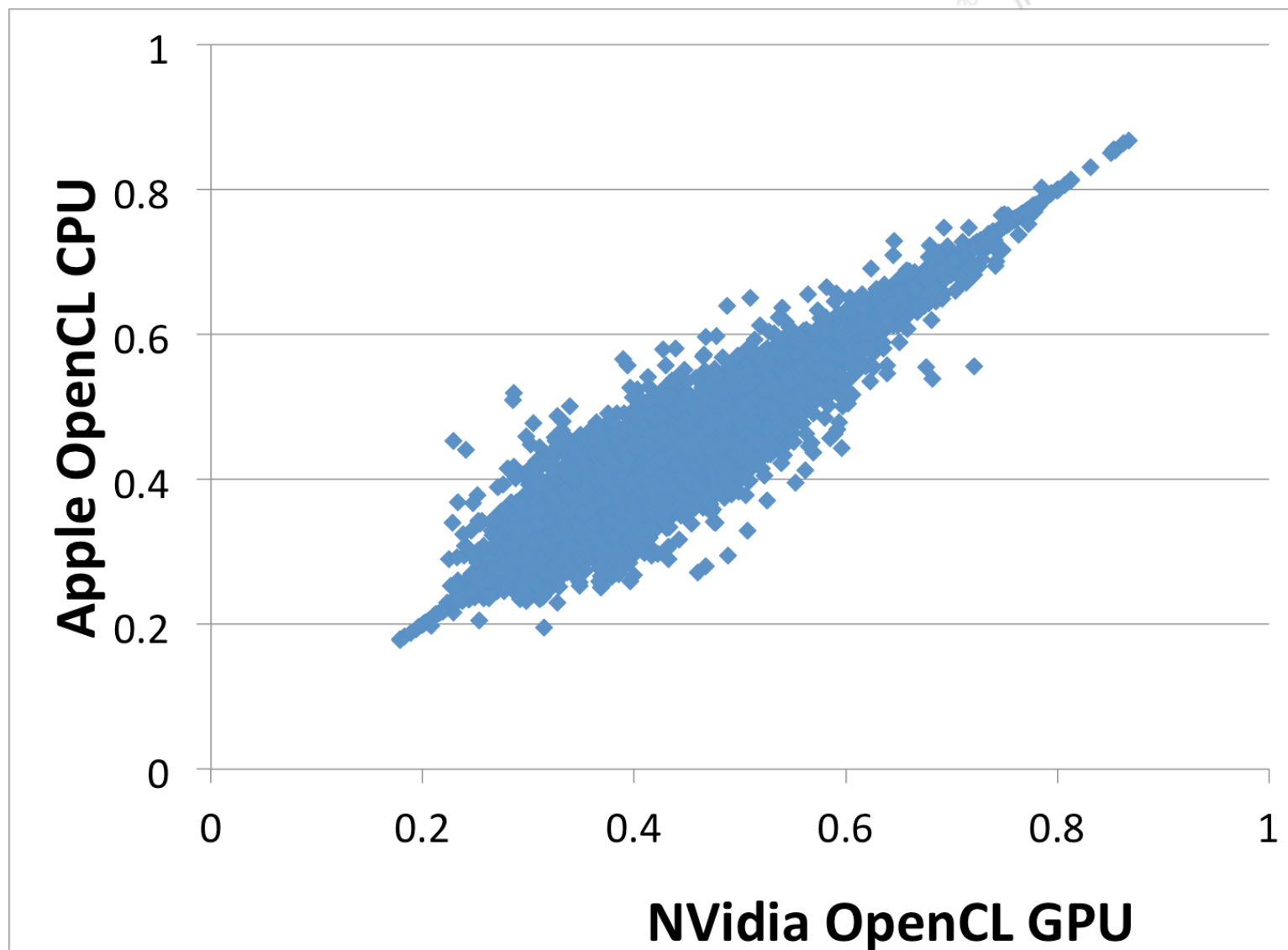
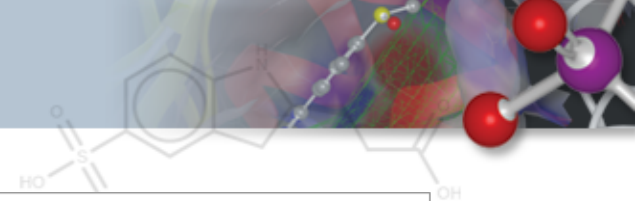
☐ Allow SSH access to machine

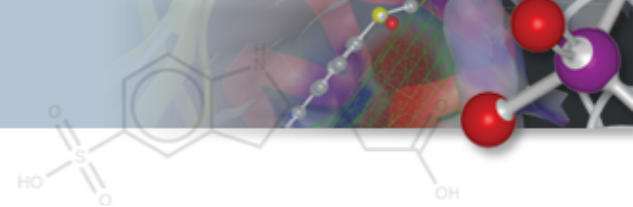
Submit Restart service



What's in the “chasm”?

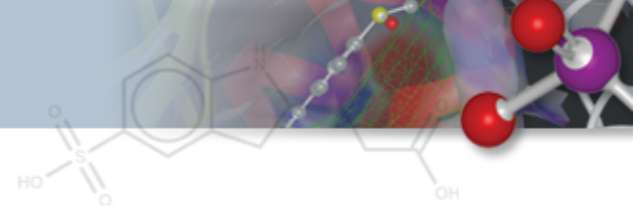
- “GPUs are hard to deploy”
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- “The results aren't bitwise comparable”
- “There's nothing else to run on the GPU”





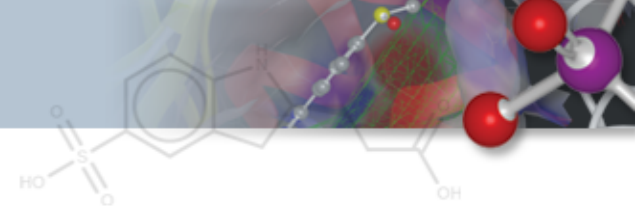
Wish list

- Numerical analysis profiler
- Profile what is creating the most numerical error
- Understand the realized dynamic range
 - Should I use half, float, double, long double?



What's in the “chasm”?

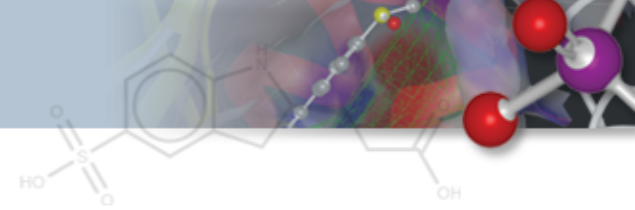
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OpenEye product sheet

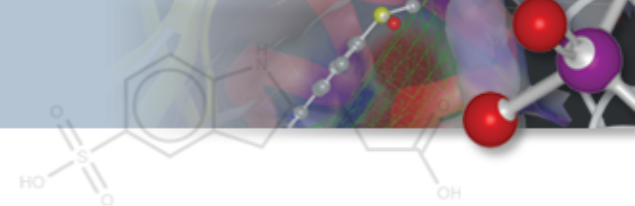
- AFITT
- BROOD
- FRED
- EON
- OMEGA
- pKa Prospector
- QUACPAC
- ROCS
- SZMAP
- SZYBKI
- VIDA
- OEChemTK
- DepictTK
- DockingTK
- GraphemeTK
- GraphSimTK
- LexichemTK
- MedChemTK
- MolPropTK
- OmegaTK
- QuacPacTK
- SpicoliTK
- SzmapTK
- SzybkiTK
- ZapTK





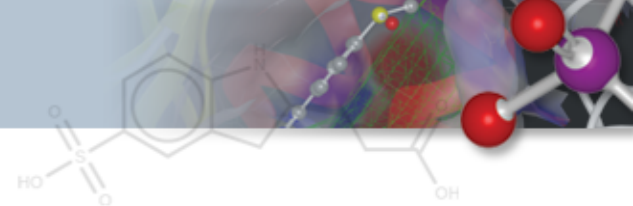
C++ future

- SYCL looks great
 - C++ -> OpenCL SPIR is promising
- C++ working group on parallelism is promising
 - But 10 years till usable
- Need to make accelerator computing ubiquitous
 - Convert to the church of Eric Berdahl

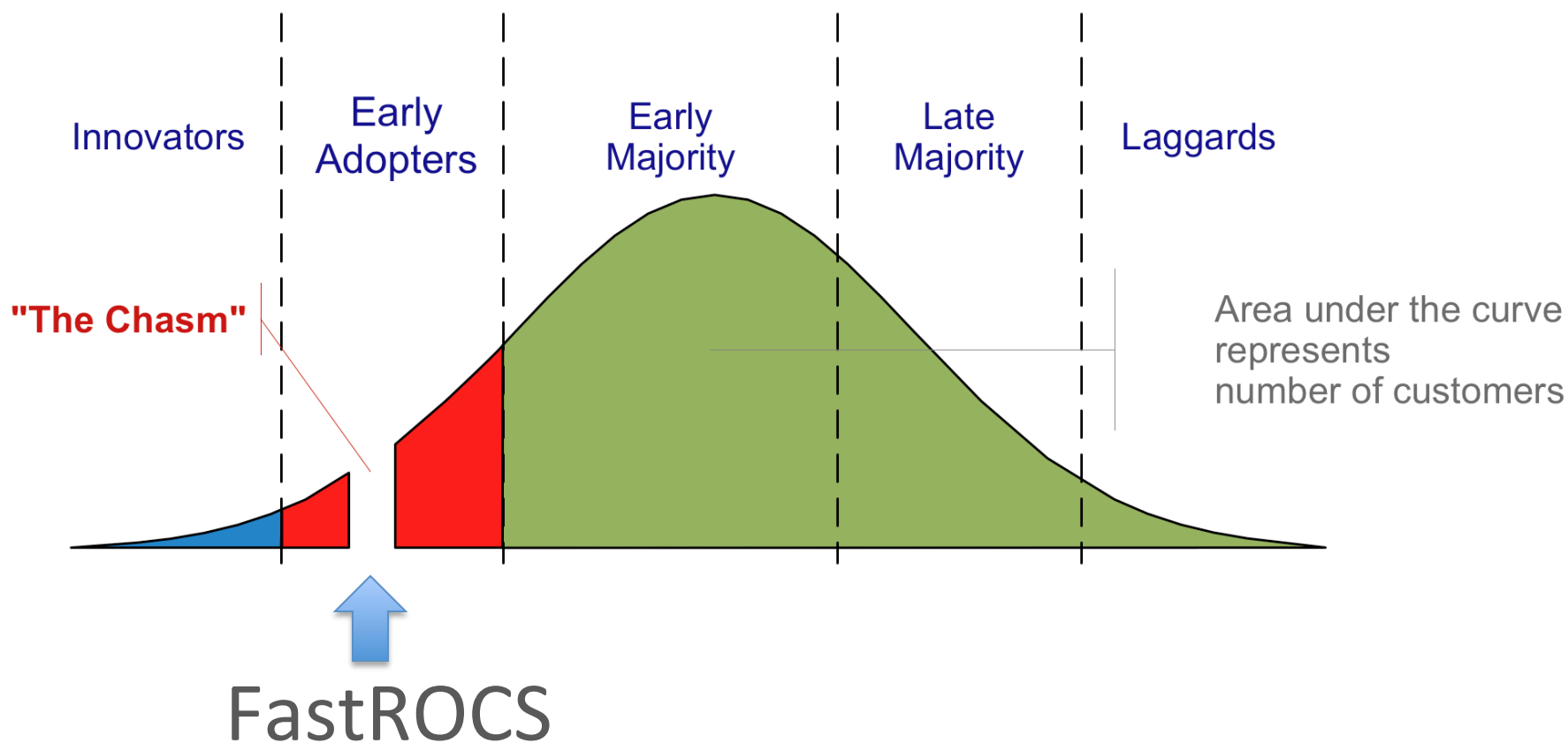


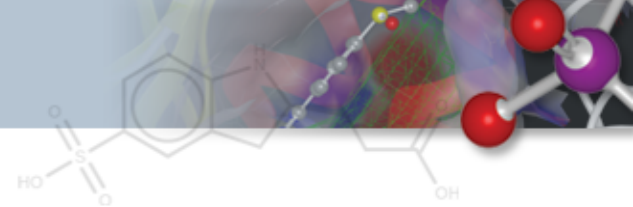
What's in the “chasm”?

- “GPUs are hard to deploy”
 - Mature-ish
- “GPUs are hard to maintain”
 - Maturing
- “The results aren't bitwise comparable”
 - Good challenge for academia
- “There's nothing else to run on the GPU”
 - Good challenge for everyone here



Technology Adoption Lifecycle





OpenEye Scientific Software

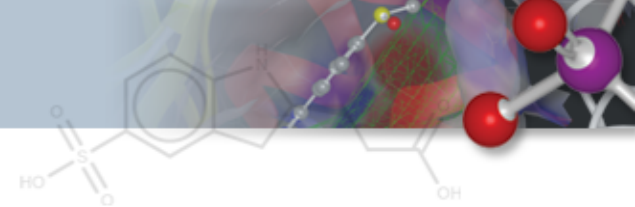
For more information, please contact us:

business@eyesopen.com

support@eyesopen.com

www.eyesopen.com

+1-505-473-7385



Acknowledgements

- Dave Mullally (HP)
 - For access to test hardware
- Nikolai Sakharnykh (NVidia)
 - For a great effort porting to CUDA
- Herb Sutter (Microsoft)
 - For insight about Little's Law